

Inner product and angle between two vectors. Note that a function is a special case of a vector.

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Define **angle** between two vectors x & y : $x \cdot y = |x| \cdot |y| \cdot \cos(\theta)$

$$\theta(x, y) := \arccos\left(\frac{x \cdot y}{|x| \cdot |y|}\right)$$

Projection of x into y is the inner product of (x, y) in the direction of y .

$$\text{projection}(x, y) := \frac{(x \cdot y) \cdot y}{(|y|)^2}$$

Example:

$$x := \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \quad y := \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$$

Mathcad note: there is a "." after x , so that we can do symbolic evaluation later on this worksheet.

$$\theta(x, y) = 54.736 \cdot \text{deg}$$

Schwarz inequality: $(|x \cdot y| \leq |x| \cdot |y|) = 1$ "1" for "true"

Triangular inequality: $(|x + y| \leq |x| + |y|) = 1$

$$\text{projection}(x, y) = \begin{pmatrix} 0.333 \\ 0.333 \\ 0.333 \end{pmatrix} \quad \sum \text{projection}(x, y) = 1 \quad |\text{projection}(x, y)| = 0.577$$

Cross product (torque = radius \times force)

$$\text{torque}(r, F) := r \times F$$

$$\phi(r, F) := \arcsin\left(\frac{|r \times F|}{|r| \cdot |F|}\right)$$

An example:

$$r := \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \quad F := \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \quad \text{torque}(r, F) = \begin{pmatrix} 0 \\ -1 \\ 1 \end{pmatrix} \quad \phi(r, F) = 54.736 \cdot \text{deg}$$

Define **inner product** between two functions (and the definition of magnitude naturally follows)

$$\text{prod}(f, g) := \int_{-1}^1 f(x) \cdot g(x) \, dx \quad \text{mag}(f) := \sqrt{\text{prod}(f, f)} \quad \theta(f, g) := \text{acos}\left(\frac{\text{prod}(f, g)}{\text{mag}(f) \cdot \text{mag}(g)}\right)$$

An example:

$$\begin{aligned} f_1(x) &:= 1 & f_2(x) &:= x & f_3(x) &:= x^2 & f_4(x) &:= x^3 \\ \theta(f_1, f_2) &= 90 \cdot \text{deg} & \theta(f_1, f_3) &= 41.81 \cdot \text{deg} & \theta(f_1, f_4) &= 90 \cdot \text{deg} & & 1 \text{ \& } x^2 \text{ are not orthogonal.} \\ & & \theta(f_2, f_3) &= 90 \cdot \text{deg} & \theta(f_2, f_4) &= 23.578 \cdot \text{deg} & & x \text{ \& } x^3 \text{ are not orthogonal.} \\ & & & & \theta(f_3, f_4) &= 90 \cdot \text{deg} & & \end{aligned}$$

Gram-Schmidt Process.

Problem Statement: Given power series f_j , construct orthogonal vectors/functions e_j . Below ee_j are the analytical results.

$$\begin{aligned} e_1(x) &:= f_1(x) & e_1(x) &:= 1 & ee_1(x) &:= 1 \\ e_2(x) &:= f_2(x) - \frac{\text{prod}(e_1, f_2)}{\text{prod}(e_1, e_1)} \cdot e_1(x) & \frac{\text{prod}(e_1, f_2)}{\text{prod}(e_1, e_1)} &= 0 & \dots \text{ o.k.} & \\ e_2(x) &\Rightarrow x & ee_2(x) &:= x \end{aligned}$$

Mathcad got overwhelmed between e_2 and e_3 and subsequently failed to calculate e_3 and e_4 correctly.

$$\begin{aligned} \text{prod}(e_1, f_3) &= 0.667 & \frac{\text{prod}(e_1, f_3)}{\text{prod}(e_1, e_1)} &= 0.333 & \text{prod}(e_2, f_3) &= 2.974 \cdot 10^{-4} & \frac{\text{prod}(e_2, f_3)}{\text{prod}(e_2, e_2)} &= 1 \\ \text{prod}(e_1, e_1) &= 2 & \text{prod}(e_2, e_2) &= 2.974 \cdot 10^{-4} \end{aligned}$$

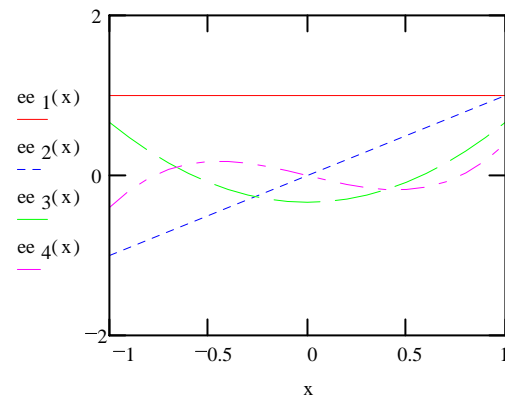
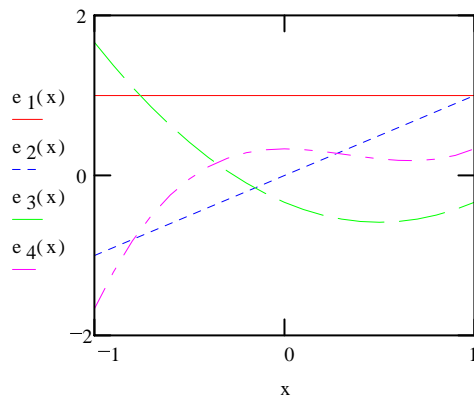
The ratio of the inner product in the second term should have been 0, not 1:

$$\begin{aligned} \text{prod}(ee_2, f_3) &= 0 & \frac{\text{prod}(ee_2, f_3)}{\text{prod}(ee_2, ee_2)} &= 0 \\ \text{prod}(ee_2, ee_2) &= 0.667 \end{aligned}$$

$$\begin{aligned} e_3(x) &:= f_3(x) - \frac{\text{prod}(e_1, f_3)}{\text{prod}(e_1, e_1)} \cdot e_1(x) - \frac{\text{prod}(e_2, f_3)}{\text{prod}(e_2, e_2)} \cdot e_2(x) \\ e_3(x) &\Rightarrow x^2 - \frac{1}{3} & ee_3(x) &:= x^2 - \frac{1}{3} \\ e_4(x) &:= f_4(x) - \frac{\text{prod}(e_1, f_4)}{\text{prod}(e_1, e_1)} \cdot e_1(x) - \frac{\text{prod}(e_2, f_4)}{\text{prod}(e_2, e_2)} \cdot e_2(x) - \frac{\text{prod}(e_3, f_4)}{\text{prod}(e_3, e_3)} \cdot e_3(x) \\ e_4(x) &\Rightarrow x^3 - \frac{3}{5} \cdot x & ee_4(x) &:= x^3 - \frac{3}{5} \cdot x \end{aligned}$$

$x := -1, -0.9..1$

Comparison of numerical results and analytical results.



Check: (Numerical results are no good.)

$$\begin{aligned} \theta(e_1, e_2) &= 90 \cdot \text{deg} & \theta(e_1, e_3) &= 89.177 \cdot \text{deg} & \theta(e_1, e_4) &= 90 - 0.878i \cdot \text{deg} \\ & & \theta(e_2, e_3) &= 27.937 \cdot \text{deg} & \theta(e_2, e_4) &= 90 + 48.149i \cdot \text{deg} \\ & & & & \theta(e_3, e_4) &= 90 + 53.176i \cdot \text{deg} \end{aligned}$$

Check: (Analytical results are o.k.)

$$\begin{aligned} \theta(ee_1, ee_2) &= 90 \cdot \text{deg} & \theta(ee_1, ee_3) &= 90 \cdot \text{deg} & \theta(ee_1, ee_4) &= 90 \cdot \text{deg} \\ & & \theta(ee_2, ee_3) &= 90 \cdot \text{deg} & \theta(ee_2, ee_4) &= 90 \cdot \text{deg} \\ & & & & \theta(ee_3, ee_4) &= 90 \cdot \text{deg} \end{aligned}$$

Orthogonal polynomials (**Legendre Polynomials** .. un-normalized):

$$P_0(x) := 1 \quad P_1(x) := x \quad P_2(x) := \frac{1}{2} \cdot (3 \cdot x^2 - 1) \quad P_3(x) := \frac{1}{2} \cdot (5 \cdot x^3 - 3 \cdot x) \quad P_4(x) := \frac{1}{8} \cdot (35 \cdot x^4 - 30 \cdot x^2 + 3)$$

$$\begin{aligned} \theta(P_0, P_1) &= 90 \cdot \text{deg} & \theta(P_0, P_2) &= 90 \cdot \text{deg} & \theta(P_0, P_3) &= 90 \cdot \text{deg} & \theta(P_0, P_4) &= 90 \cdot \text{deg} \\ & & \theta(P_1, P_2) &= 90 \cdot \text{deg} & \theta(P_1, P_3) &= 90 \cdot \text{deg} & \theta(P_1, P_4) &= 90 \cdot \text{deg} \\ & & & & \theta(P_2, P_3) &= 90 \cdot \text{deg} & \theta(P_2, P_4) &= 90 \cdot \text{deg} \\ & & & & & & \theta(P_3, P_4) &= 90 \cdot \text{deg} \end{aligned}$$

Generating equation for Legendre polynomials:

$$P(x, n) := \text{if} \left(n=1, 1, \frac{2 \cdot n - 1}{n} \cdot x \cdot P(x, n-1) - \frac{n-1}{n} \cdot P(x, n-2) \right)$$

The above is a recursive definition that does not work in version 5, but may work in version 6 (provided that we take care of $n=0$).

Legendre Polynomials of the Second Kind .. not quite mutually orthogonal based on the preceding definition of inner product:

$$Q_0(x) := \ln \left(\sqrt{\frac{1+x}{1-x}} \right) \quad Q_1(x) := x \cdot Q_0(x) - 1 \quad Q_2(x) := P_3(x) \cdot Q_0(x) - \frac{3}{2} \cdot x$$

$$\theta(Q_0, Q_1) = 90 \cdot \text{deg} \quad \theta(Q_0, Q_2) = 143.375 \cdot \text{deg} \quad \theta(Q_1, Q_2) = 71.86 \cdot \text{deg}$$

For certain applications, a different interval is useful.

$$\text{prod}(f, g) := \int_0^{2 \cdot \pi} f(x) \cdot g(x) \, dx \quad \text{mag}(f) := \sqrt{\text{prod}(f, f)}$$

$$\theta(f, g) := \text{acos}\left(\frac{\text{prod}(f, g)}{\text{mag}(f) \cdot \text{mag}(g)}\right)$$

An example:

$f(x) := \sin(x)$	$g(x) := \cos(x)$	$\theta(f, g) = 90 \cdot \text{deg}$	$\text{mag}(f)^2 = 1 \cdot \pi$	$\text{mag}(g)^2 = 1 \cdot \pi$
$f(x) := \sin(x)$	$g(x) := \sin(2 \cdot x)$	$\theta(f, g) = 90 \cdot \text{deg}$		
$f(x) := \sin(x)$	$g(x) := \sin(3 \cdot x)$	$\theta(f, g) = 90 \cdot \text{deg}$		
$f(x) := \cos(x)$	$g(x) := \cos(2 \cdot x)$	$\theta(f, g) = 90 \cdot \text{deg}$		
$f(x) := \sin(2 \cdot x)$	$g(x) := \cos(3 \cdot x)$	$\theta(f, g) = 90 \cdot \text{deg}$		
$f(x) := \sin(x)$	$g(x) := \sin\left(x + \frac{\pi}{2}\right)$	$\theta(f, g) = 90 \cdot \text{deg}$	← Another interpretation of angle	
$f(x) := \sin(x)$	$g(x) := \sin\left(x + \frac{\pi}{4}\right)$	$\theta(f, g) = 45 \cdot \text{deg}$	← Another interpretation of angle	

Thus, sine and cosine functions have the nice property that they are orthogonal to each other.

For other applications, a weighting factor may be included.

$$w(x) := \frac{1}{\sqrt{1-x^2}}$$

$$\text{prod}(f, g) := \int_{-1}^1 w(x) \cdot f(x) \cdot g(x) \, dx \quad \text{mag}(f) := \sqrt{\text{prod}(f, f)}$$

$$\theta(f, g) := \text{acos}\left(\frac{\text{prod}(f, g)}{\text{mag}(f) \cdot \text{mag}(g)}\right)$$

Example: Chebychev Polynomials.

$T_0(x) := 1$	$T_1(x) := x$	$T_2(x) := 2 \cdot x^2 - 1$	$T_3(x) := 4 \cdot x^3 - 3 \cdot x$	$T_4(x) := 8 \cdot x^4 - 8 \cdot x^2 + 1$
$\theta(T_0, T_1) = 90 \cdot \text{deg}$	$\theta(T_0, T_2) = 90 \cdot \text{deg}$	$\theta(T_0, T_3) = 90 \cdot \text{deg}$	$\theta(T_0, T_4) = 90 \cdot \text{deg}$	
	$\theta(T_1, T_2) = 90 \cdot \text{deg}$	$\theta(T_1, T_3) = 90 \cdot \text{deg}$	$\theta(T_1, T_4) = 90 \cdot \text{deg}$	
		$\theta(T_2, T_3) = 90 \cdot \text{deg}$	$\theta(T_2, T_4) = 90 \cdot \text{deg}$	
			$\theta(T_3, T_4) = 90 \cdot \text{deg}$	

Yet for other applications, a semi-infinite interval is useful, and a weighting factor may be included.

$$w(x) := \exp(-x)$$

$$\text{prod}(f, g) := \int_0^{\infty} w(x) \cdot f(x) \cdot g(x) \, dx \quad \text{mag}(f) := \sqrt{\text{prod}(f, f)}$$

$$\theta(f, g) := \text{acos}\left(\frac{\text{prod}(f, g)}{\text{mag}(f) \cdot \text{mag}(g)}\right)$$

Example: **Laguerre polynomials.**

$$\begin{aligned} L_0(x) &:= 1 & L_1(x) &:= 1 - x & L_2(x) &:= 2 - 4x + x^2 \\ L_3(x) &:= 6 - 18x + 9x^2 - x^3 & L_4(x) &:= 24 - 96x + 72x^2 - 16x^3 + x^4 \end{aligned}$$

Although the integrals do not converge numerically (because the upper integration limit is ∞), they converge to 0 symbolically.

$$\int_0^{\infty} \exp(-x) \cdot L_0(x) \cdot L_1(x) \, dx = \int_0^{\infty} \exp(-x) \cdot L_0(x) \cdot L_1(x) \, dx \rightarrow 0$$

not converging

$$\int_0^{\infty} \exp(-x) \cdot L_1(x) \cdot L_2(x) \, dx \rightarrow 0$$

The angles, calculated symbolically, are:

$$\begin{aligned} \theta(L_0, L_1) &\rightarrow \frac{1}{2} \cdot \pi & \theta(L_0, L_2) &\rightarrow \frac{1}{2} \cdot \pi & \theta(L_0, L_3) &\rightarrow \frac{1}{2} \cdot \pi & \theta(L_0, L_4) &\rightarrow \frac{1}{2} \cdot \pi \\ & & \theta(L_1, L_2) &\rightarrow \frac{1}{2} \cdot \pi & \theta(L_1, L_3) &\rightarrow \frac{1}{2} \cdot \pi & \theta(L_1, L_4) &\rightarrow \frac{1}{2} \cdot \pi \\ & & & & \theta(L_2, L_3) &\rightarrow \frac{1}{2} \cdot \pi & \theta(L_2, L_4) &\rightarrow \frac{1}{2} \cdot \pi \\ & & & & & & \theta(L_3, L_4) &\rightarrow \frac{1}{2} \cdot \pi \end{aligned}$$

Yet for other applications, an infinite interval is useful, and a weighting factor may be included.

$$w(x) := \exp(-x^2)$$

$$\text{prod}(f, g) := \int_{-\infty}^{\infty} w(x) \cdot f(x) \cdot g(x) \, dx \quad \text{mag}(f) := \sqrt{\text{prod}(f, f)}$$


$$\theta(f, g) := \text{acos}\left(\frac{\text{prod}(f, g)}{\text{mag}(f) \cdot \text{mag}(g)}\right)$$

Example: Hermite polynomials.

$$H_0(x) := 1 \quad H_1(x) := 2 \cdot x \quad H_2(x) := 4 \cdot x^2 - 2 \quad H_3(x) := 8 \cdot x^3 - 12 \cdot x \quad H_4(x) := 16 \cdot x^4 - 48 \cdot x^2 + 12$$

Although the integrals do not converge numerically (because the upper integration limit is ∞), they converge to 0 symbolically.

$$\int_{-\infty}^{\infty} \exp(-z^2) \cdot H_0(z) \cdot H_1(z) \, dz = \int_{-\infty}^{\infty} \exp(-z^2) \cdot H_0(z) \cdot H_1(z) \, dz \rightarrow 0$$



$$\int_{-\infty}^{\infty} \exp(-z^2) \cdot H_1(z) \cdot H_2(z) \, dz \rightarrow 0$$

The angles, calculated symbolically, are:

$$\begin{aligned} \theta(H_0, H_1) &\Rightarrow \frac{1}{2} \cdot \pi & \theta(H_0, H_2) &\Rightarrow \frac{1}{2} \cdot \pi & \theta(H_0, H_3) &\Rightarrow \frac{1}{2} \cdot \pi & \theta(H_0, H_4) &\Rightarrow \frac{1}{2} \cdot \pi \\ & & \theta(H_1, H_2) &\Rightarrow \frac{1}{2} \cdot \pi & \theta(H_1, H_3) &\Rightarrow \frac{1}{2} \cdot \pi & \theta(H_1, H_4) &\Rightarrow \frac{1}{2} \cdot \pi \\ & & & & \theta(H_2, H_3) &\Rightarrow \frac{1}{2} \cdot \pi & \theta(H_2, H_4) &\Rightarrow \frac{1}{2} \cdot \pi \\ & & & & & & \theta(H_3, H_4) &\Rightarrow \frac{1}{2} \cdot \pi \end{aligned}$$